

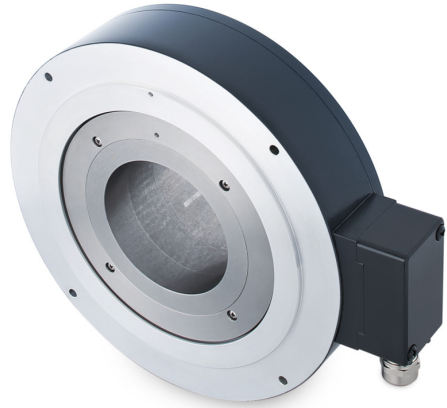
## HG 22

Incremental encoder with optical sensing

Through hollow shaft  $\varnothing 90 \dots 120$  mm / 720 ... 4000 pulses per revolution

### Overview

- Large axial and radial displacement of the shaft permitted
- Fit for high operating speed
- Robust and wearless
- Max. 4000 pulses per revolution
- Output stage TTL with regulator UB 9...26 VDC



**HUBNER**  
**BERLIN**  
A Baumer Brand

### Technical data

#### Technical data - electrical ratings

Voltage supply	9...26 VDC 5 VDC $\pm 5$ %
Consumption w/o load	$\leq 100$ mA
Pulses per revolution	720 ... 4000
Output signals	K1, K2, K0 + inverted
Reference signal	Zero pulse, width 90°
Output frequency	$\leq 120$ kHz
Phase shift	90° $\pm 20$ °
Duty cycle	40...60 %
Sensing method	Optical
Output stages	HTL TTL/RS422
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-3
Approval	CE UL approval / E217823

#### Technical data - mechanical design

Size (flange)	$\varnothing 227$ mm
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#### Technical data - mechanical design

Shaft type	$\varnothing 90 \dots 120$ mm (through hollow shaft)
Axial tolerance	-0.5 ... 1.5 mm (with zero pulse) -0.5 ... 2.5 mm (without zero pulse)
Radial tolerance	$\pm 0.05$ mm (with zero pulse) $\pm 0.2$ mm (without zero pulse)
Protection EN 60529	IP 44
Operating speed	$\leq 12000$ rpm
Material	Housing: aluminium Shaft: stainless steel
Rotor moment of inertia	67.3 kgcm <sup>2</sup>
Operating temperature	-30...+70 °C
Resistance	IEC 60068-2-6 Vibration 10 g, 10-2000 Hz IEC 60068-2-27 Shock 100 g, 6 ms
Weight approx.	5.8 kg
Connection	Terminal box (2x with option M) Flange connector M23, 12-pin (2x with option M)

### Optional

- Electrical connection with flange connector and mating connector
- Redundant sensing (option M)

## HG 22

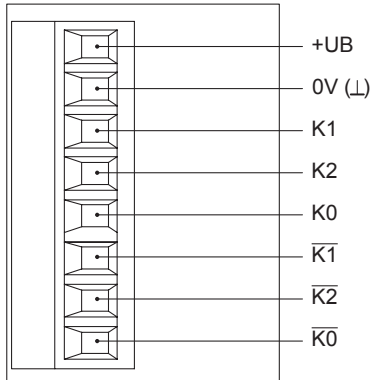
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### Terminal assignment

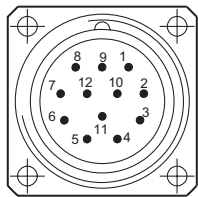
#### View A (see dimension)

Connecting terminal terminal box



#### View B (see dimension)

Assignment flange connector



Flange connector M23,  
male, 12-pin,  
clockwise (CW)

Pin	Assignment
1	$\overline{K2}$
2	dnu
3	K0
4	$\overline{K0}$
5	K1
6	$\overline{K1}$
7	dnu
8	K2
9	dnu
10	0V (L)
11	dnu
12	+UB

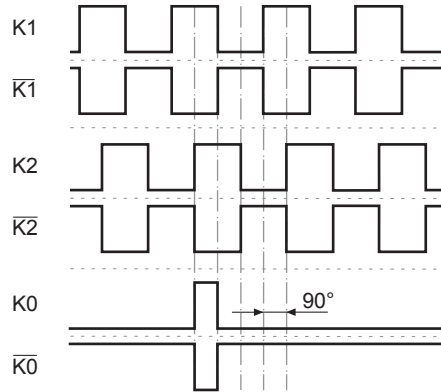
### Terminal significance

+UB	Voltage supply
0V (L)	Ground
K1	Output signal channel 1
$\overline{K1}$	Output signal channel 1 inverted
K2	Output signal channel 2 (offset by 90° to channel 1)
$\overline{K2}$	Output signal channel 2 inverted
K0	Zero pulse (reference signal)
$\overline{K0}$	Zero pulse inverted
dnu	Do not use

### Output signals

#### HTL/TTL

At positive rotating direction (see dimension)

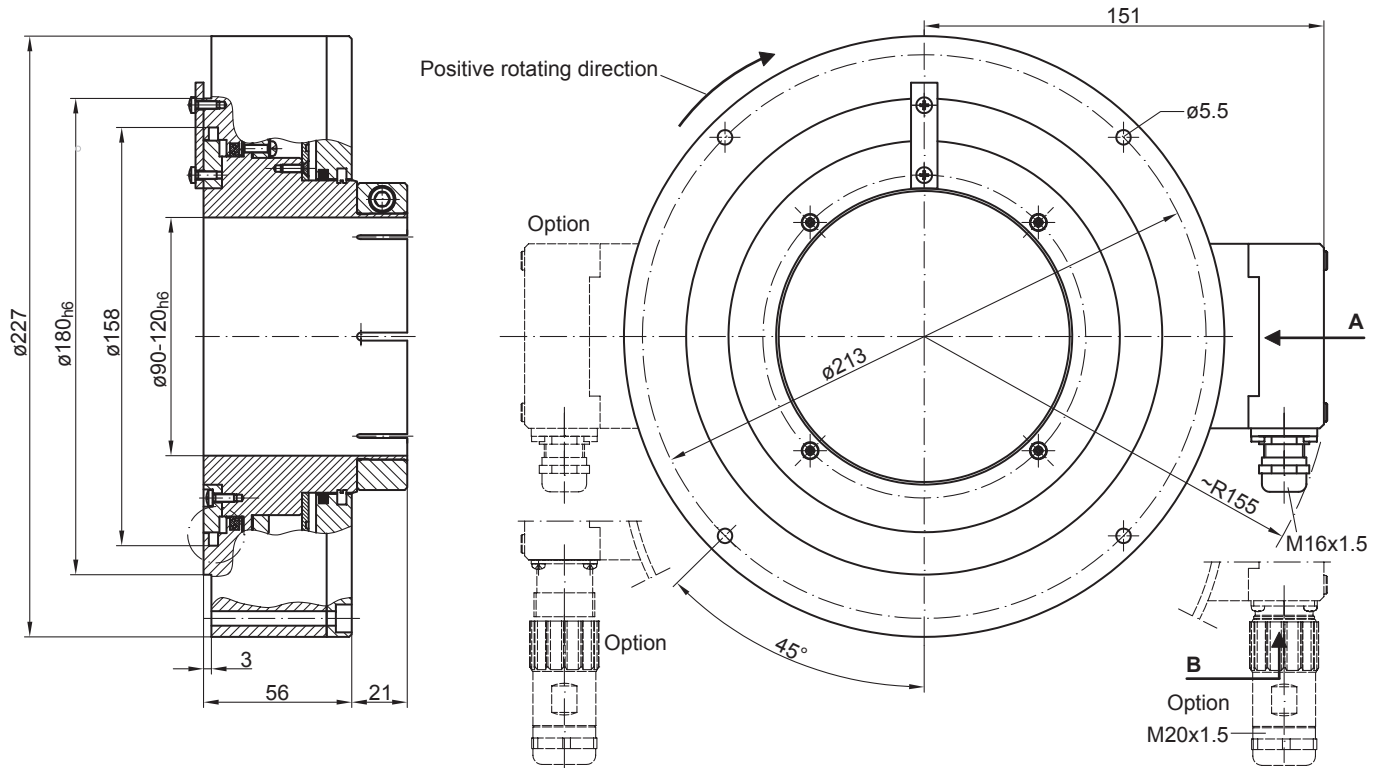


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## Dimensions



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**Ordering reference**

	HG22	#	DN	####	###
<b>Product</b>					
Encoder without bearings - incremental	HG22				
<b>Redundant sensing</b>					
Without redundant sensing					
With redundant sensing		M			
<b>Output signals</b>					
K1, K2, K0			DN		
<b>Pulse number<sup>(1)</sup></b>					
720				720	
1800				1800	
2400				2400	
4000				4000	
<b>Voltage supply / output stage</b>					
9...26 VDC / output stage HTL (C) with inverted signals					CI
5 VDC / output stage TTL with inverted signals					TTL
9...30 VDC / output stage TTL with inverted signals					R

(1) Other pulse numbers on request.