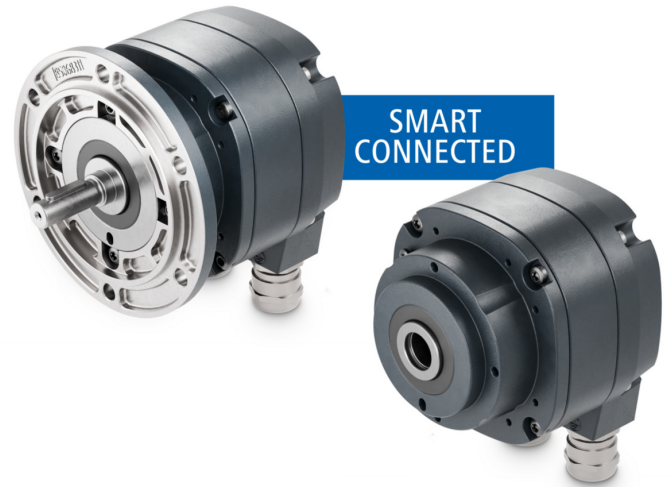


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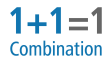
Incremental HeavyDuty encoders for demanding machinery and asynchronous drives with three switching outputs

Overview

- Protection IP66, IP67
- Shaft insulation 3.5 kV
- Corrosion protection CX
- Operating temperature -40...+100 °C
- Signal outputs with automatic temperature compensation for stable signals up to 350 m (HTL-P) or 550 m (TTL)
- Sealed and user-friendly field termination
- Extended protection circuit
- Parameterization of the pulses per revolution and the switching outputs
- Standstill, speed, direction and status monitoring and display with Baumer Sensor Suite or using the switches
- 4-fold sealing concept for protection against abrasive dust, humid and salty moisture and temperature changes



Picture similar



Technical data

Technical data - electrical ratings

Voltage supply	4.75...30 VDC (Vin = Vout, HTL/TTL)
Consumption w/o load	≤100 mA
Pulses per revolution	1 ... 32768
Further pulses per revolution	Freely parameterizable with Baumer Sensor Suite
Phase shift	Typ. 90 °
Duty cycle	Typ. 50 %
Reference signal	Zero pulse, width 90° or 180°
Sensing method	Optical
Output frequency	≤200 kHz
Output signals	K1, K2, K0 + inverted
Output stages	HTL-P (power linedriver) TTL
Shaft insulation	Suitable up to 3.5 kV
Transmission length	≤350 m at 100 kHz (HTL-P) ≤550 m at 100 kHz (TTL)
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-4
Approval	CE UL approval / E217823 CSA

Technical data - mechanical design

Size (flange)	ø105 mm, length 94 mm
Shaft type	ø16G7 mm (blind hollow shaft) ø11 x 30 mm (solid shaft with key)
Admitted shaft load	≤350 N axial ≤450 N radial
Mounting type	Hollow shaft: central screw Solid shaft: EURO flange B10
Protection EN 60529	IP 66 / IP 67
Operating speed	≤6000 rpm (mechanical)

Technical data - mechanical design

Operating torque	≤6 Ncm
Rotor moment of inertia	160 gcm ²
Material	Housing: aluminium, powder-coated Shaft: stainless steel
Operating temperature	-40...+100 °C
Resistance	IEC 60068-2-6 Vibration 20 g, 10-2000 Hz IEC 60068-2-27 Shock 300 g, 6 ms 1 Mio. brake shocks
Corrosion protection	IEC 60068-2-52 Salt mist for ambient conditions CX according to ISO 12944-2
Connection	Terminal box with pluggable push in terminal blocks and cable gland M20

Technical data - digital switches

Switching outputs	Output (Push)
Number of switching outputs	3

Technical data - digital speed switches

Function	Detection of overspeed and underspeed
Max. number of switching outputs	3

Parametrization	Speed range Hysteresis Switching delay
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Speed setting resolution	0.1 rpm
Switching accuracy	± 2 % (up to ±1 rpm at 50 rpm)

Technical data - standstill monitoring

Function	Detection of standstill and creep
Max. number of switching outputs	1

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Technical data

Technical data - standstill monitoring

Parametrization	Dwell time
	Standstill position window

Activation Speed	±2 rpm
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Technical data - direction of rotation

Function	Detection and display of the direction of rotation
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Technical data - direction of rotation

Max. number of switching outputs	1
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Parametrization	Hysteresis
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Incremental HeavyDuty encoders for demanding machinery and asynchronous drives with three switching outputs

Baumer Sensor Suite

Monitoring

The following information is displayed with the Baumer Sensor Suite:

- Encoder settings
- Speed and position over time
- Current speed, position and temperature
- Encoder status
- Minimum and maximum temperature over entire service life
- Total operating time
- Total revolutions
- Switch monitoring
 - Switch status
 - Speed over time per switch with switching window
 - Switch status over time
 - Direction of rotation status
 - Status of standstill monitoring

Parameterization

The following parameters can be set via USB-C access with the Baumer Sensor Suite:

- Number of lines per mechanical revolution
- Output stages
- Reference length and phase
- Setting the user units
- Switching outputs
 - Switching active high, active low
 - Speed switch
 - Direction of rotation switch
 - Standstill switch
- Time behavior for switching outputs
 - Minimum switch-on time (On)
 - Minimum switch-off duration (Off)

Parameterization - encoder

Pulses per revolution	Selection: 50, 500, 512, 1000, 1024, 2048, 2500, 4096, 5000 + free input
Output stages	HTL-P (power linedriver) TTL
Rotating direction	CW, CCW
Width of zero pulse	90°, 180° (reference signal)

Parameterization - digital switches

Min. switch-on time	1...1000 ms
Min. switch-off time	1...1000 ms

Parameterization - digital speed switch

Function	Speed switch with adjustable speed limits and switching delay to filter out short-term speed peaks
Switching output	Active high / active low
Upper/lower speed range	±2 ... 6000 rpm
Hysteresis	0...50 %
Switching delay time	0...5000 ms (0 ms default)

Parameterization - standstill monitoring

Function	Reliable creep detection through position monitoring if the speed falls below a specified speed within a defined time window
Switching output	Active high / active low
Dwell time	10...1000000 ms
Creep Window	1...100°

Parameterization - direction of rotation

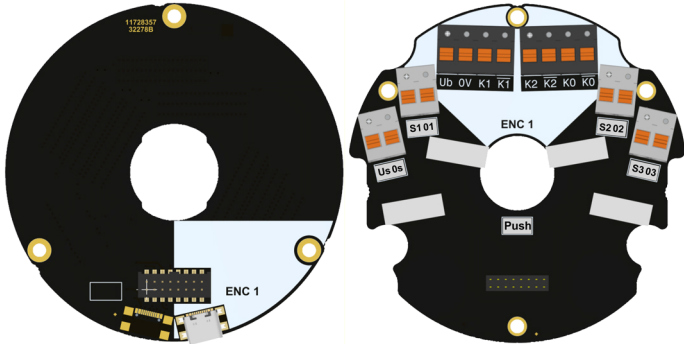
Function	Direction detection with adjustable hysteresis
Switching output	Active high / active low
Hysteresis	1...100°

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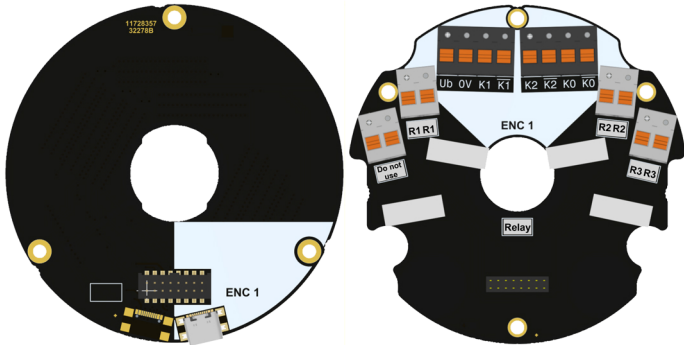
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Terminal assignment

Output (push)



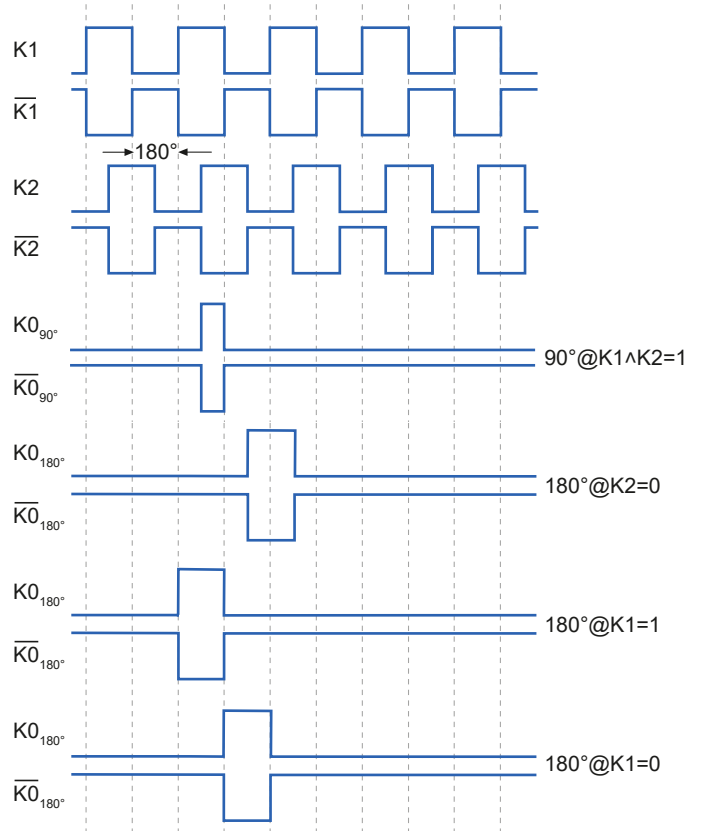
Output (relay)



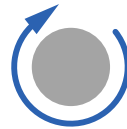
Terminal significance

U _b	Voltage supply
0V	Ground
K0	Zero pulse (reference signal)
$\overline{K0}$	Zero pulse inverted
K1	Output signal channel 1
$\overline{K1}$	Output signal channel 1 inverted
K2	Output signal channel 2
$\overline{K2}$	Output signal channel 2 inverted
Us	Voltage supply - push output
0s	Ground - push output
S1	Push switching output 1
S2	Push switching output 2
S3	Push switching output 3
01	Ground - push output 1
02	Ground - push output 2
03	Ground - push output 3
R1	Relay output 1
R2	Relay output 2
R3	Relay output 3
USB ENC1	USB-C for parameterization

Output signals



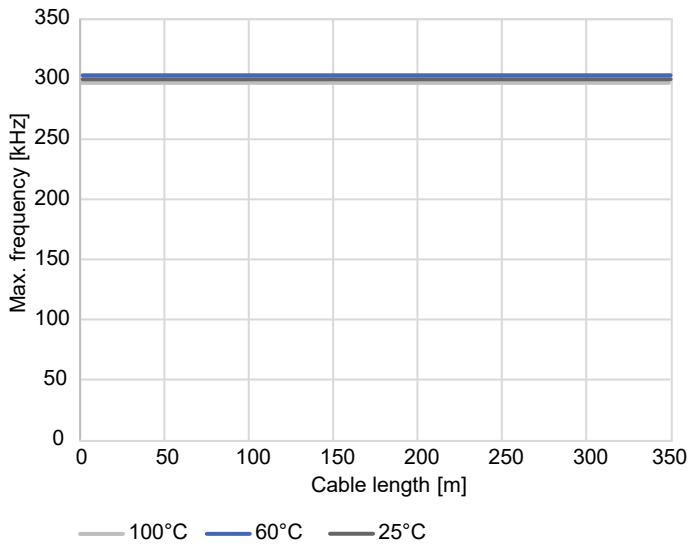
With positive direction of rotation / clockwise, with view on the encoder shaft



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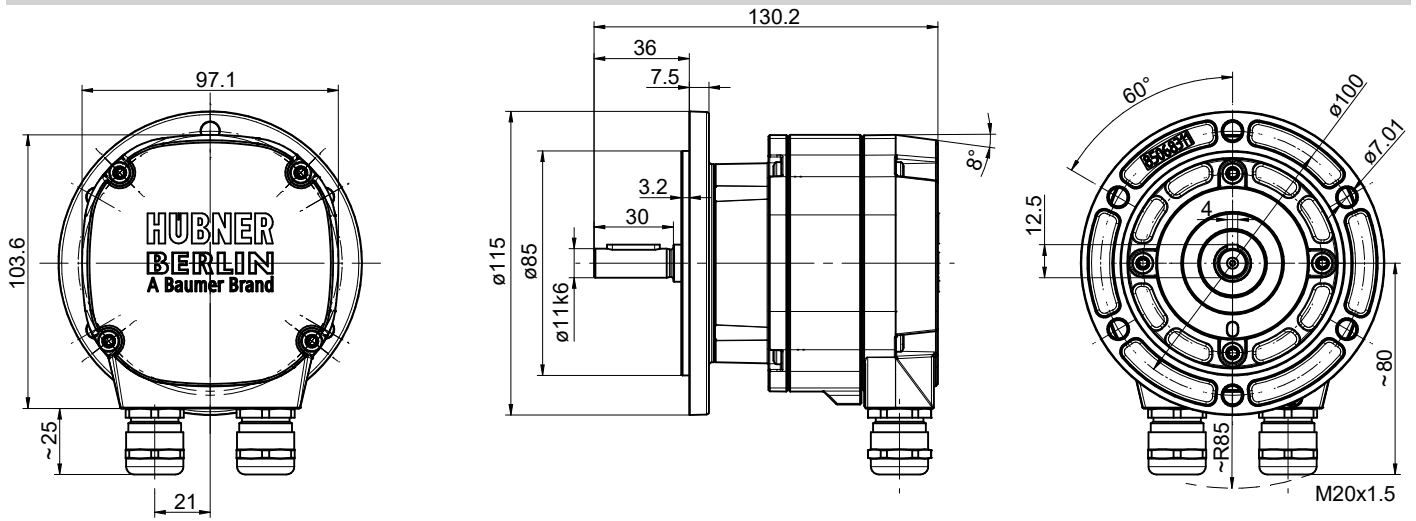
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Derating



Max. frequency over cable length and temperature, Ub 24 V

Dimensions

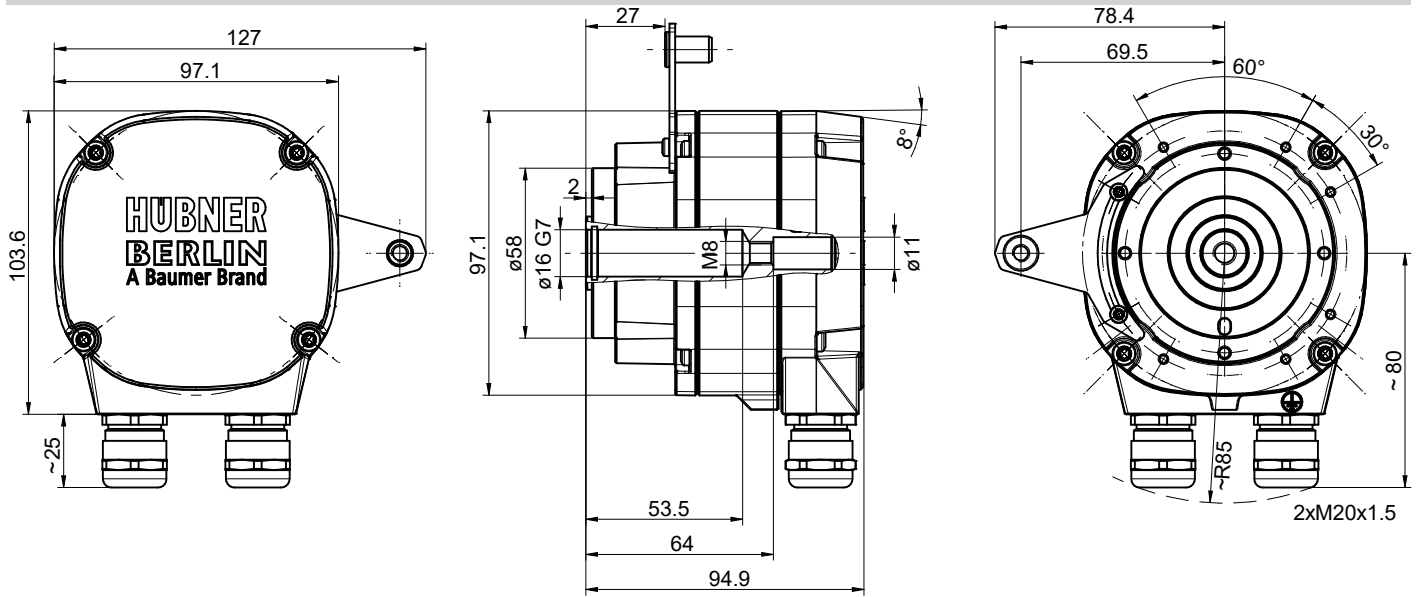


Solid shaft, cable gland

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Incremental HeavyDuty encoders for demanding machinery and asynchronous drives with three switching outputs

Dimensions



Blind hollow shaft, cable gland (torque plate can be mounted at different positions)

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Incremental HeavyDuty encoders for demanding machinery and asynchronous drives with three switching outputs

Ordering reference					
Product	Shaft	Pulses per revolution, output	Connection	Comment	Material number
HOG1090	Solid shaft ø11 mm	Parameterization & monitoring at customer	2 x cable gland M20	SMART, 3 x push	EHO1090-11731294
		Parameterization & monitoring at customer	2 x cable gland M20	SMART, 3 x relay	EHO1090-11731295
	Blind hollow shaft ø16G7 mm	Parameterization & monitoring at customer	2 x cable gland M20	SMART, 3 x push	EHO1090-11731296
		Parameterization & monitoring at customer	2 x cable gland M20	SMART, 3 x relay	EHO1090-11731297