

# HMG10-T - EtherCAT

Through hollow shaft

EtherCAT / 13 bit ST / 16 bit MT / Speed switch

## Overview

- Interface EtherCAT
- Magnetic sensing method
- Resolution: singleturn 13 bit, multiturn 16 bit
- Function display via LEDs
- Multiturn sensing with Energy Harvesting technology "MicroGen", without gear or battery
- Two-sided bearing system with hybrid bearings
- Special protection against corrosion CX (C5-M)



Picture similar

**HUBNER**  
BERLIN  
A Baumer Brand

**microGen**  
Energy Harvesting

## Technical data

### Technical data - electrical ratings

Voltage supply	10...30 VDC
Short-circuit proof	Yes
Consumption w/o load	≤200 mA
Initializing time	≤ 500 ms after power on
Interface	EtherCAT
Function	Multiturn
Transmission rate	100 MBaud
Device address	Automatic address designation
Steps per revolution	8192 / 13 bit
Number of revolutions	65536 / 16 bit
Additional outputs	Square-wave TTL/HTL, TTL/RS422
Sensing method	Magnetic
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-3
Programmable parameters	Steps per revolution Number of revolutions Preset, scaling, rotating direction
Diagnostic function	Position or parameter error
Status indicator	DUO-LED and LEDs link/activity in bus connecting box 4 LEDs in device back side
Approval	CE UL approval / E217823

### Technical data - electrical ratings (speed switch)

Switching accuracy	± 2 % (or 1 Digit)
Switching outputs	1 output (Open collector, solid state relay on request)

### Technical data - electrical ratings (speed switch)

Output switching capacity	30 VDC; ≤100 mA
Switching delay time	≤20 ms
<b>Technical data - mechanical design</b>	
Size (flange)	ø105 mm
Shaft type	ø16...20 mm (through hollow shaft)
Flange	Support plate, 360° freely positionable
Protection EN 60529	IP 66 / IP 67
Operating speed	≤6000 rpm
Range of switching speed	ns (off) = ±2...6000 rpm
Operating torque typ.	10 Ncm
Rotor moment of inertia	950 gcm <sup>2</sup>
Admitted shaft load	≤450 N axial ≤650 N radial
Material	Housing: aluminium alloy Shaft: stainless steel
Corrosion protection	IEC 60068-2-52 Salt mist for ambient conditions CX (C5-M) according to ISO 12944-2
Operating temperature	-40...+85 °C
Relative humidity	95 % non-condensing
Resistance	IEC 60068-2-6 Vibration 30 g, 10-2000 Hz IEC 60068-2-27 Shock 400 g, 1 ms
Weight approx.	2.2 kg (depending on version)
Connection	Bus connecting box Terminal box incremental

## Optional

- Integrated speed switch
- Additional output incremental with zero pulse

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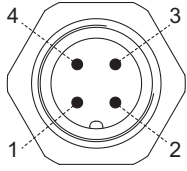
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## Terminal assignment

### View A1 (see dimension)

View into connector bus "voltage supply"

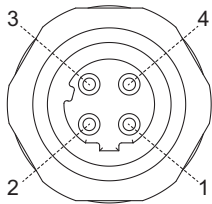


Connector M12 (male)  
4-pin, A-coded

Pin	Connection
1	UB
2	dnu
3	GND
4	dnu

### View A2 and A3 (see dimension)

View into connector bus „data transmission“



Connector M12 (female)  
4-pin, D-coded

Pin	Connection
1	TxD+
2	RxD+
3	TxD-
4	RxD-

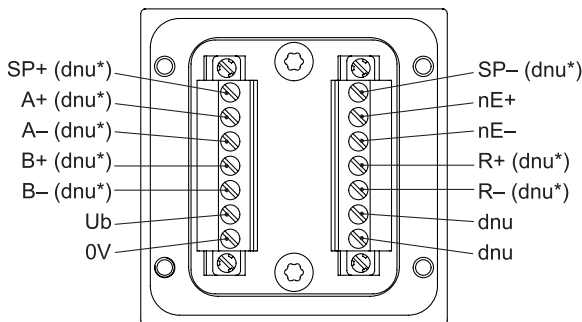
### View B (see dimension)

Connecting terminal terminal box

Speed switch /

additional output II (HTL, TTL)

\* Assignment depends on encoder version



## Terminal significance

### Bus interface

Connection	Description
GND	Ground for UB
UB	Voltage supply 10...30 VDC
TxD+	Transmission data+
TxD-	Transmission data-
RxD+	Receiving data+
RxD-	Receiving data-
dnu	Do not use

Ub	Voltage supply
0V	Ground
A+	Output signal channel 1
A-	Output signal channel 1 inverted
B+	Output signal channel 2 (offset by 90° to channel 1)
B-	Output signal channel 2 inverted
R+	Zero pulse (reference signal)
R-	Zero pulse inverted
nE+	System OK+ / error output
nE-	System OK- / error output inverted
SP+	DSL_OUT1 / speed switch (open collector, solid state relay on request)
SP-	DSL_OUT2 / speed switch (0V, solid state relay on request)
dnu	Do not use

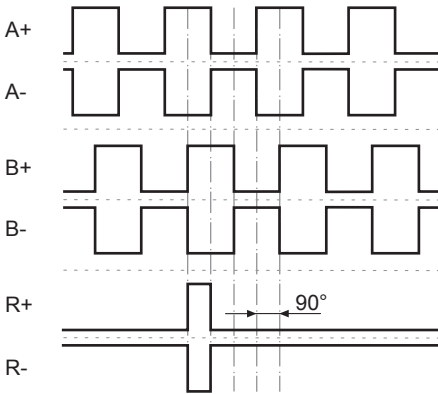
## EtherCAT features

Bus protocol	EtherCAT
Device profile	CoE (CANopen over EtherCAT) DSP406
Features	<ul style="list-style-type: none"> <li>100 MBaud Ethernet</li> <li>Automatic address designation</li> <li>Distributed clock for precise synchronization. Optional device configuration as „Reference Clock“</li> <li>Factory setting 10 byte PDO, configurable 4 byte PDO / 2 byte PDO for shorter cycle times</li> </ul>
Process data	Position value, Warnings, System time
Cycle times	Depending on sensor type, enabled scaling functionality and length of PDO. Minimum cycle time: 62,5 µs
Synchronization	<ul style="list-style-type: none"> <li>0x00 Free Run, not synchronized</li> <li>0x03 Distributed clocks DC, synchronized with SYNCO/SYNC1 Event</li> </ul>

## Output signals

### Additional output II (HTL/TTL)

At positive rotating direction (see dimension)



## Trigger level

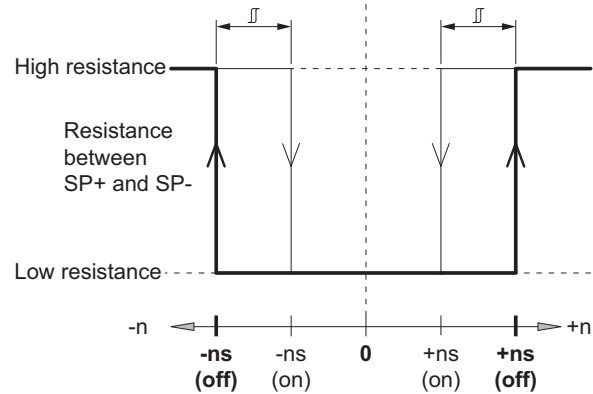
### Incremental HTL/TTL

Electrically isolated:  
The output TTL/HTL ( $V_{in} = V_{out}$ ) at the additional output II is electrically isolated and requires a separate power supply.

Trigger level	TTL/RS422
High / Low	$\geq 2.5 \text{ V} / \leq 0.5 \text{ V}$
Transmission length	$\leq 550 \text{ m @ } 100 \text{ kHz}$
Output frequency	$\leq 600 \text{ kHz}$
Trigger level	TTL/HTL ( $V_{in} = V_{out}$ )
High / Low	$\geq 2.5 \text{ V} / \leq 0.5 \text{ V}$ (TTL) $\geq U_b - 3 \text{ V} / \leq 1.5 \text{ V}$ (HTL)
Transmission length	$\leq 550 \text{ m @ } 100 \text{ kHz}$ (TTL) $\leq 350 \text{ m @ } 100 \text{ kHz}$ (HTL)
Output frequency	$\leq 600 \text{ kHz}$ (TTL); $\leq 350 \text{ kHz}$ (HTL)

## Switching characteristics

### Speed switch



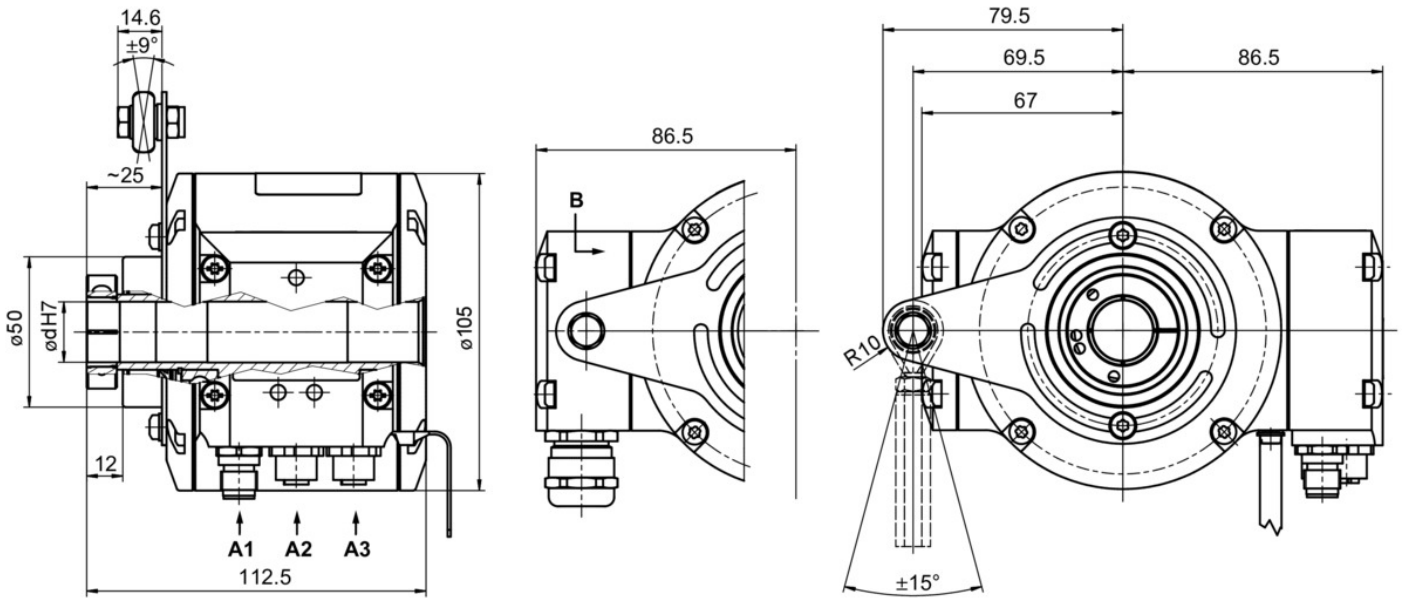
n	Speed
+ns (off)	Switch-off speed at shaft rotation in positive rotating direction (see dimension).
-ns (off)	Switch-off speed at shaft rotation in negative rotating direction (see dimension).
	Switching hysteresis $\Delta n$ : 10...100 % (factory setting = 10 % min. 1 Digit)
+ns (on)	Switch-on speed at shaft rotation in positive rotating direction (see dimension).
-ns (on)	Switch-on speed at shaft rotation in negative rotating direction (see dimension).

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## Dimensions



Through hollow shaft with terminal box

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## Ordering reference

	HMG10	#	-	T	H	#	.	#	#	EC	3	.	#	0	0	#	A
<b>Product</b>	HMG10																
Absolute encoder	HMG10																
<b>Digital speed switch</b>																	
Without			-														
With			D														
<b>Shaft type</b>																	
Through hollow shaft				T													
<b>Flange (Hollow shaft)</b>																	
Support (Support plate) for torque arm, hybrid bearings					H												
<b>Protection class</b>																	
IP 66 and IP 67, optimized for dusty, abrasive environment						D											
IP 66 and IP 67, optimized for oily, wet environment						L											
<b>Through hollow shaft</b>																	
Ø16 mm, clamping ring, A end																	C
Ø20 mm, clamping ring, A end																	F
Ø16 mm, keyway																	P
<b>Connection</b>																	
Bus connecting box with 3 connectors M12, radial																	3
Bus connecting box with 3 connectors M12, radial + terminal box with 1 cable gland M20, radial																	G
<b>Supply voltage (field bus)</b>																	
10...30 VDC, EtherCAT										EC							
<b>Resolution singleturn position</b>																	
13 Bit																	3
<b>Resolution multiturn position</b>																	
No multiturn signal																	0
16 Bit																	6
<b>Resolution speed</b>																	
No speed signal																	0
<b>Resolution supplement I</b>																	
No additional output I																	0
<b>Resolution supplement II</b>																	
No additional output II																	0
512 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated																	1
512 ppr TTL (RS422), 6 channels																	2
1024 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated																	5
1024 ppr TTL (RS422), 6 channels																	6
2048 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated																	9
2048 ppr TTL (RS422), 6 channels																	4
3072 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated																	7
3072 ppr TTL (RS422), 6 channels																	8
4096 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated																	K
4096 ppr TTL (RS422), 6 channels																	J
5000 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated																	G
5000 ppr TTL (RS422), 6 channels																	H
8192 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated																	Q
8192 ppr TTL (RS422), 6 channels																	P
<b>Operating temperature</b>																	
-40...+85 °C																	A

(1) Please specify the exact switching speed in addition to the part number (factory setting).

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It may happen that not all variants of the type code can be combined. Any restrictions can be found in the web configurator at [www.baumer.com](http://www.baumer.com) or on request.

## Accessories

### Mounting accessories

11043628	Torque arm M6, length 67...70 mm
11004078	Torque arm M6, length 120...130 mm ( $\geq 71$ mm)
11002915	Torque arm M6, length 425...460 mm ( $\geq 131$ mm)
11054917	Torque arm M6 insulated, length 67...70 mm
11082677	Torque arm M6 insulated, length 425...460 mm ( $\geq 131$ mm)
11077197	Mounting kit for torque arm size M6 and earthing strap
11238694	CAM12.WS13-11238694